Improved Detection of Gait Abnormalities in Parkinson's disease using IMU Sensors



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Motivation

- ◆ Automated tracking of Parkinson's disease (PD) motor symptoms during daily activities requires robust and clinically-relevant sensor metrics ¹.
- ◆ Bradykinesia, a major motor symptom of PD, is activity-dependent and requires advanced tools for assessment that include gait.

 Bradykinesia can manifest during gait as a reduction in arm swing, leg velocity, range of movement, and heel-toe dynamics, which are difficult to capture with conventional sensors such as accelerometers.

◆ Recent advances in wearable inertial (IMU) sensors may provide an enhanced means of recording joint kinematic of bradykinesia gait disorders.

Objective

To evaluate the ability of IMU sensor-based metrics to identify gait impairments associated with body bradykinesia in patients with Parkinson's disease during unscripted activities of daily living.

Approach

• Body bradykinesia assessment during gait was based on impairments listed in Item 31 of UPDRS.

◆ An automated classifier (neural network) was designed to isolate gait activity from other activities based on leg sensor data.

• Five gait metrics were analyzed using angular velocity (gyroscope) and compared during presence and absence of bradykinesia.

Data Collection

Subject Population

PD Subjects Demographics	
Number	n = 6
Age (y)	57.5 ± 12.5
Male/Female	4/2
Disease Duration(y)	8.6 ± 5.4
Total Data	1000 min
Bradykinesia Prevalence* (%)	58.7
Hoehn-Yahr (ON)	11-111,

* % of Total Data w/ bradykinesia

Data Acquisition Protocol

◆ Data were acquired from 2 wireless IMU sensors (Trigno IM - Delsys Inc) from forearm and shank – see Figure

◆ Data were recorded continuously for 3 hours in a simulated home setting during unscripted activities.

◆ Video recordings were acquired and annotated by movement disorder experts to identify activity type and presence/absence of body bradykinesia (based on Item 31 of UPDRS)

Methods

♦ Gait impairment metrics were calculated on the basis of angular velocity magnitude and range of movement from gyroscope data. [Refer to Analysis section]

◆ Statistical comparisons (Mann-Whitney-Wilcoxon test) were computed to test the discriminability of gait impairment metrics for Bradykinesia and Non-Bradykinesia portions of the gait data. [Refer to Results section]

Analysis



Results



Unaffected





Conclusion



IMU Sensor

Sensor Placement Location:

Shiwani B³, Roy SH^{1,2}, Kline JC^{1,2}, Saint-Hilaire MH⁴, Thomas CA⁴, Gennert MA³, De Luca G^{1,2}

◆ The numbers [1-5] in the figure refer to the five sensor-based gait metrics that were derived to quantify gait impairments associated with bradykinesia. ◆ Raw gyroscope data from upper and lower limb are compared with raw Accelerometer data for the same IMU recording. • These comparisons illustrate the greater precision in identifying data features from the angular velocity plots compared to accelerometer plots.

The numbers [1-5] identify the bradykinesia gait impairments described in the Analysis. Corresponding raw angular velocity for instances with and without bradykinesia are analyzed. The results demonstrate that IMU sensors provide objective gait metrics with significant discriminability for bradykinesia.

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• The work demonstrates the viability to develop robust and clinically-relevant metrics for improved detection of gait abnormalities in PD. A subsequent study [see Adjacent Poster: Roy et al. "Autonomous Tracking of Body Bradykinesia..."] utilized these impairment metrics as features to train a neural network classifier to detect body bradykinesia and achieved <5% error during unscripted activities in a population of n=16 PD subjects.

References

